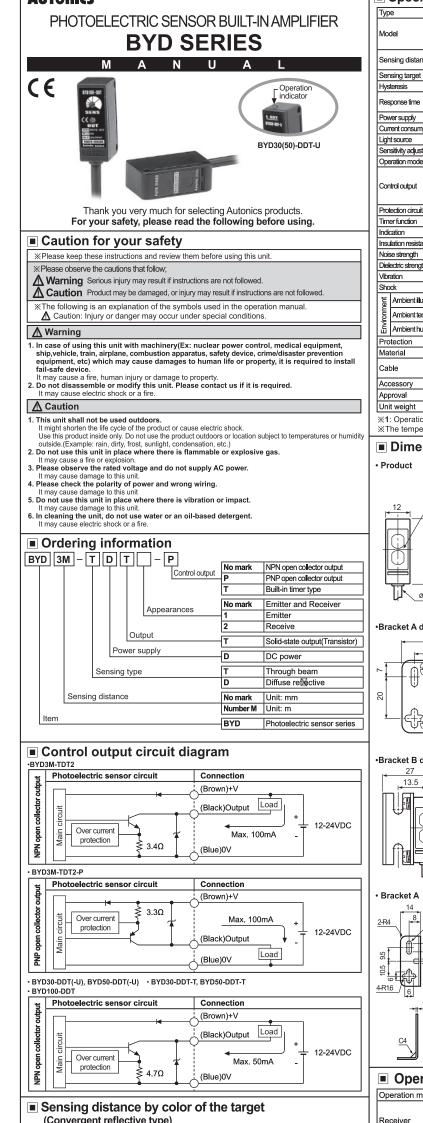
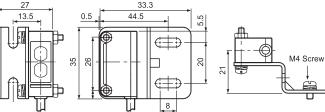
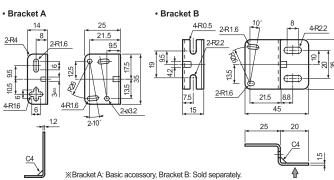
Autonics



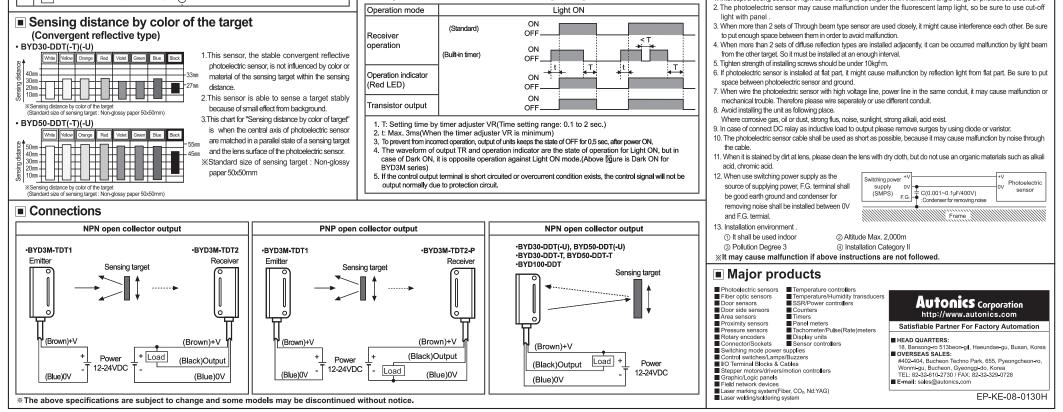
Specifications Convergent relective Diffuse relective hrough beam BYD30-DDT BYD30-DDT-U (※1) NPN output type BYD50-DDT PNP output type BYD50-DDT-U (※1) BYD100-DDT BYD3M-TDT BYD3M-TDT-P BYD30-DDT-T (%2) BYD50-DDT-T (%2) 10 to 30mm 10 to 50mm 100mm Sensing distance (Non-glossy white paper 50×50mm) Non-glossy white paper 50×50mm) (Non-glossy white paper 50×50mm) Opaque materials of Min. ø6mm Translucent, Opaque materials Max. 10% at sensing distance Max. 25% at sensing distance Operation: Max. 3ms Operation: Max. 3ms Response time Max. 1ms Return: Max. 100ms Return: Max. 100ms(When the time adjuster VR is minimum) 12 - 24 VDC ±10% (Ripple P-P: Max. 10%) Max. 30mA Max. 35mA Current consumptior Infrared LED Fixed Adjuster VR Fixed Sensitivity adjustmen Light ON Med Operation mode Dark ON(Light ON: Option) NPN or PNP open collector outpu NPN open collector output Load voltage: Max. 30VDC Load voltage: Max. 30VDC Load current: Max. 50mA Residual voltage: Max. 1V Load current: Max. 100mA •Residual voltage - NPN: Max.1V, PNP: Max. 2.5V Reverse polarity protection, Short-circuit protection Built-in(OFF delay) delay Time: Max. 0.1 to 2 sec.(adjuster VR) Operation indicator: Red LED Min. 20MΩ(at 500VDC megger) Insulation resistance $\pm 240V$ the square wave noise(pulse width: 1µs) by the noise simulator 1,000VAC 50/60Hz for 1 minute Dielectric strength 1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours 500m/s²(50G) in X, Y, Z directions for 3 times Ambient illumination Sunlight: Max. 11,0001x, Incandescent lamp: Max. 3,000lx(Receiver illumination) Ambient temperature -20 to 65°C, Storage: -25 to 70°C 35 to 85%RH, Storage: 35 to 85%RH Ambient humidity Standard type: IP64(IEC standards)/(※1),(※2): IP50(IEC standards) IP64(IEC standards) IP50(IEC standards) Case: ABS, Sensing part: Acryl ø3.5mm, 3-wire, Length: 2m(Emitter of through-beam type: ø3.5mm, 2-wire, Length: 2m) (AWG24, Core diameter: 0.08mm, Number of cores: 40, Insulator diameter: 1mm) VR adjustment driver, Mounting bracket A, M3 Screws, Nuts Mounting bracket A, M3 Screws, Nuts CE Approx. 70g Approx. 150g X1: Operation indicator is on top. X2: OFF delay timer is built-in. XThe temperature or humidity mentioned in Environment indicates a non freezing or condensation environment. Dimension Mounting & Adjustment Through beam type (Unit: mm) Adjust Supply the power after set the emitter and the receiver facing each other. Set them in the middle after checking the operation range of the indicator by Operation indicator 0 Right/Left Receive (BYD30(50)-DDT-U Type) adjusting or rotating the receiver and the emitter right and left slightly. 18 Adjusting and down direction in the same way as above. After adjustment, fix them after checking the stable operation by Optical Emitter 2-ø3.2 _3 putting the sensing target at the optical axis Xiff the sensing target is translucent or smaller than 6mm, it is not able to sense because the light of the sensor is penetrated. **M** Adjust Up/Down Diffuse reflective type 32 26 Operation indicator 1. The sensitivity should be adjusted considering the influence of behind Photoelectric 4 objects or mounting side even though it is available to use at max. sensitivity point normally. 2. Put a sensing target at the sensing distance and check the point . % Built-in timer type: Timer adjuster VR, Diffuse reflective U (a) where the operation indicator turns on by adjusting slowly the Sensing target ø3.5, 2m type: Sensitivity adjuster VR sensitivity adjuster VR from the min_sensitive point. 3. Remove the sensing target and check the point (0) where the operation indicator until turns on by adjusting the sensitivity adjuster VR.(If the operation indicator does not turn on, max sensitivity point is (0).) Optimal Bracket A dimension when mounting point 24.5 26 0.5 4. The optimal point is the center of the point (a) and (b) Optical 50 The sensing distance indicated on the specification chart is that of non-glossy white paper 50x50mm. Be sure that it can be different by size, surface and gloss of the sensing target. axis 14 L3 Max M3 Screw θ Convergent reflective type Convergent reflective type Supply the power after mounting the photo-electric sensor to the sensing place. Put the target at sensing position and adjust the sensor right and left or up and down to be at the right angle against optical axis and fix it at the stable operating position.Keep the distance min. to 50mm for BYD30-DDT(-T)(-U) or min. to 50mm for BYD50-DDT(-T)(-U) ptween photoelectric sensor and sensing target. Min. 100mm 35 26 Surrounding object (Non-reflect 小 material must be applied)

Bracket B dimension when mounting

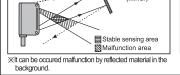


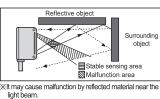


Operation mode and timing diagram



. (※1) photoelectric sensor and sensing target. 3. In case of built-in timer type, set the response time (※2) of the photoelectric sensor to the optimal status by adjusting the timer adjuster VR.(The timer of a ※1: 10 ~ 30mm: BYD30-DDT(-T)(-U) photoelectric sensor is available status.) ※2: 10 ~ 50mm: BYD50-DDT(-T)(-U) %The sensing distance indicated on the specification chart is that of non-glossy white paper 50x50mm. Be sure that it can be different by size, surface and gloss of the sensing targe Surrounding object





Accessory(Sold separately)

• SI

Slit(Model: BYD3M-Slit)				Min. Sensing target and max. sensing distance by slit's ø when attach the slits at both a receiver and an emitter.		
	۲		-\$-	Slit ø	Min. size of sensing target	Max. sensing distance
				ø1.0	Opaque materials of Min.ø0.8	500mm
Autonics	Autonics	Autonics	Autonics	ø1.5	Opaque materials of Min.ø1.5	700mm
ø2.5	ø2.0	ø1.5	ø1.0	ø2.0	Opaque materials of Min.ø2.0	1,200mm
				ø2.5	Opaque materials of Min.ø2.5	2,300mm

%This slit is for BYD3M-TDT(-P) only.

*Total 8 pieces (2 pieces of each different ø) are packed and sold separately % This slit is sticker for attachment, please remove the dirt on lens of photoelectric sensor before using it.

Caution for using

Intercept a strong source of light as like sunlight, spotlight within inclination angle range of photoelectric sensor.
The photoelectric sensor may cause malfunction under the fluorescent lamp light, so be sure to use cut-off